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$(x_1, y_1, z_1), P_2 = (x_2, y_2, z_2), O$ Figure 3-4 Distance

vector $R_{12} = P_1P_2 = R_2 - R_1$, where R_1 and R_2 are the position vectors of points P_1 and P_2 , respectively. Figure

3.3: The notion of the position vector to a point, P

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