## **Introduction To The Actuator Sensor Interface**

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Introduction to Sensors & Actuators Page 14 Basic Principle of Sensor- Sensor is a device that when exposed to a physical phenomenon (temperature, displacement, force, etc.) produces a proportional output signal (electrical, magnetic, etc.). A sensor converts a state variable of a technical process of a quality which is

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•The Actuator Sensor Interface (AS-i) is widely recognised as the simplest and lowest cost option for networking actuators and sensors in industry. •Operates at the lowest level in the fieldbus hierarchy •AS-i is designed primarily for binary (on-off) sensors and actuators although analogue elements are also easily incorporated.

## introduction to the actuator sensor Introduction to Sensors & Actuators Page 3 Objective of Mechatronics system. 3. To reduce cost of production. 4. To achieve high accuracy and precision. 5. For easy control of the system. 6 ..

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Actuators are devices that work opposite to sensors. A sensor converts a physical event into an electrical signal into a physical event when sensors are used to perform output function in a system as they control an external device.

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of a modulating sensor is a fiberoptic magnetic-field sensor in which a magnetostrictive jacket is used to convert a magnetic field into an induced strain in the optical fiber. The resulting change in the gauge length of the fiber is measured using interferometry (i.e., the strength of the magnetic field is inferred).

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Sensors and actuators are two critical components of every closed loop control system. A typical me chatronics system as shown in Fig. 16.1 consists of a sensing unit, a controller, and an actuating unit. A sensing unit can be as simple as a single sensor or can consist

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Actuator Sensor. The Actuator Sensor detects when a particular actuator receives an activation pulse. It sends a TRUE pulse when the specified actuator is activated. The sensor also sends a FALSE pulse when the specified actuator is deactivated

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?re). Sensor-actuator networks are expected to operate autonomously in unat-tended environments. They may be directly connected (using, for instance, web infrastructure) and responsive to a user (task manager) who controls the network via sinks. One or more actuator(s) may also play the role of sink(s). In fact, sinks

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